



EUSATfinder

EUSPA AI week 2026

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Outline

- Concept
- Project status
- Connectivity
- Application layer
- AI for targets identification, characterization and localisation
 - Rationale
 - Sample datasets
 - Security camera
 - UAV real time video

Concept

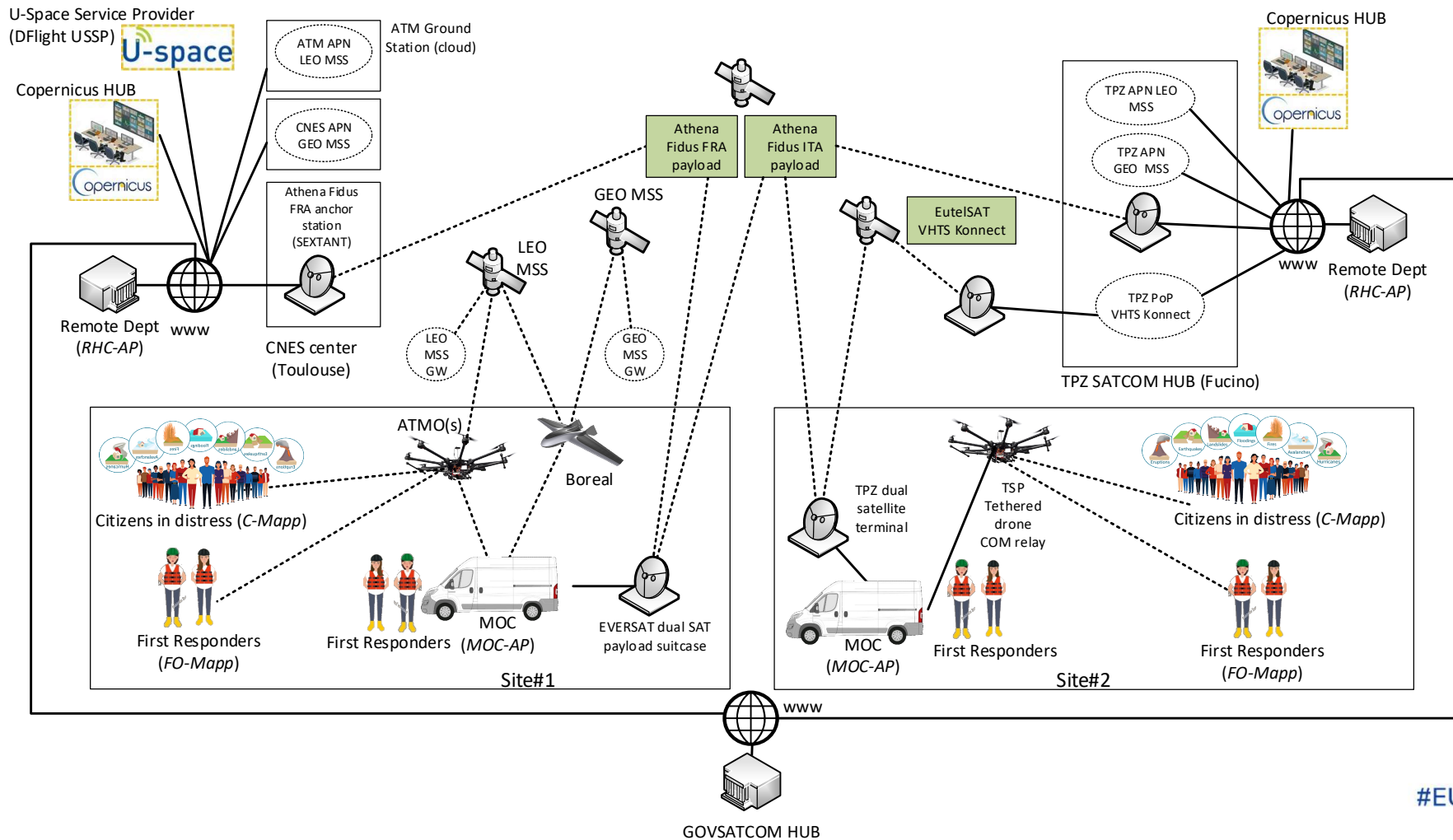


The purpose of the EUSATfinder is to provide an innovative integrated and scalable solution, to support decision maker actors in real-life during different operational phases (detection, preparedness, response, recovery and mitigation of emergencies) with particular focus to first responders' activities in situ for a disaster management.

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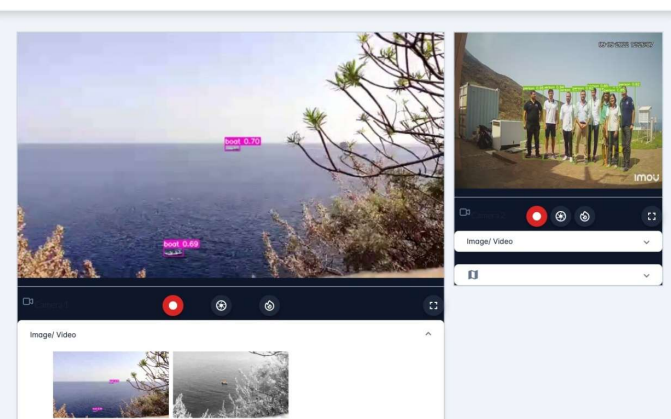
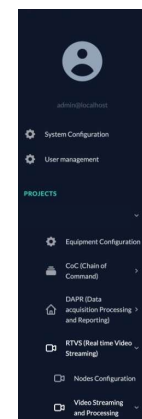
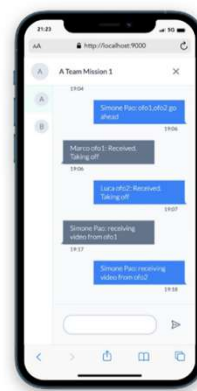
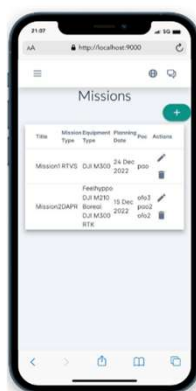


Connectivity



Application layer

- **Remote Headquarter Center application (RHC-Ap)** – Off-site, located at the First Responder's operations center and potentially integrable with other systems
- **Mobile Operations Center Application (MOC-Ap)** – On-site, for example deployed on a specialized vehicle serving as a remote operations center
- **FR' mobile application (FO-Map)** – On-site, installed on First Responders' handheld devices
- **Citizens' mobile application (C-Map)** – Installed on citizens' personal devices after registration



Target Detection, classification and Localization



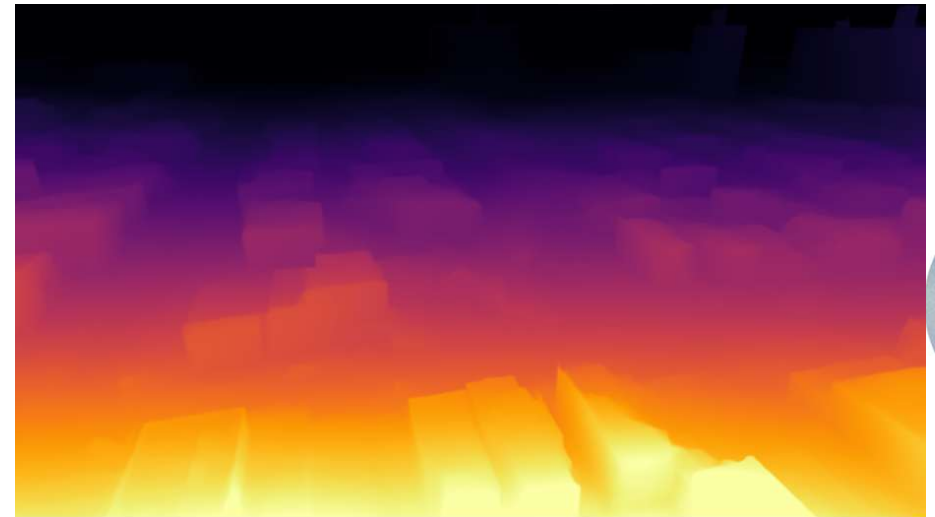
Target Detection and classification

Fine-tune a pre-trained YOLOv11 model on emergency-scene datasets to detect targets in real time



Target Localization

Estimate target position using geometric/heuristic methods and/or or transformer-based depth estimation (Depth Anything v2/v3)



Example: security camera



clideo.com

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Example: UAV real time video

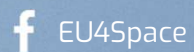




Linking space to user needs

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